

Chapter 11. **Three dimensional analytic geometry and vectors.**  
Section 11.6 **Vector functions and space curves.**

Let  $\vec{r}$  be a **vector function** whose range is a set of three-dimensional vectors.

$$\vec{r}(t) = \langle f(t), g(t), h(t) \rangle = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}$$

Functions  $f$ ,  $g$ , and  $h$  are real-valued functions called the **component functions** of  $\vec{r}$ .

The domain of  $\vec{r}$  consists of all values of  $t$  for which the expression for  $\vec{r}(t)$  is defined.

**Example 1.** Find the domain of the vector function  $\vec{r}(t) = \left\langle \sqrt{9-t}, \sqrt{t-2}, \frac{e^t}{t-5} \right\rangle$ .

**Definition.** If  $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$ , then

$$\lim_{t \rightarrow a} \vec{r}(t) = \left\langle \lim_{t \rightarrow a} f(t), \lim_{t \rightarrow a} g(t), \lim_{t \rightarrow a} h(t) \right\rangle$$

provided the limits of the component function exist.

**Example 2.** Find the limit

$$\lim_{t \rightarrow 0} \left\langle \frac{1 - \cos t}{t}, t^3, e^{-1/t^2} \right\rangle.$$

**Definition.** A vector function  $\vec{r}$  is **continuous at**  $a$  if  $\lim_{t \rightarrow a} \vec{r}(t) = \vec{r}(a)$ .

$\vec{r}$  is continuous at  $a$  if and only if its component functions  $f$ ,  $g$ , and  $h$  are continuous at  $a$ .

**Space curves.** Suppose that  $f$ ,  $g$ , and  $h$  are continuous real-valued functions on an interval  $I$ . Then the set  $C$  of all points  $(x, y, z)$  in space, where

$$x = f(t), \quad y = g(t) \quad z = h(t)$$

ant  $t$  varies throughout the interval  $I$ , is called a **space curve**. Equations

$$x = f(t), \quad y = g(t) \quad z = h(t)$$

are called **parametric equations of C** and  $t$  is called a **parameter**.

**Example 3.** Sketch the curve with the given vector equation.

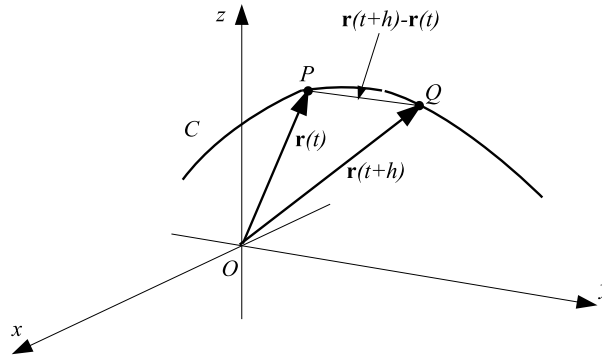
1.  $\vec{r}(t) = \langle 1 - t, t, t - 2 \rangle$

2.  $\vec{r}(t) = \langle \cos 4t, t, \sin 4t \rangle$

3.  $\vec{r}(t) = \langle \cos t, \sin t, \sin 5t \rangle$

**Derivatives and integrals.** The **derivative**  $\vec{r}'$  of a vector function  $\vec{r}$  is

$$\frac{d\vec{r}}{dt} = \vec{r}'(t) = \lim_{h \rightarrow 0} \frac{\vec{r}(t+h) - \vec{r}(t)}{h}$$



The vector  $\vec{r}'(t)$  is called the **tangent vector** to the curve defined by  $\vec{r}$  at the point  $P$ , provided that  $\vec{r}'(t)$  exists and  $\vec{r}'(t) \neq \vec{0}$ . The **tangent line** to  $C$  at  $P$  is defined to be the line through  $P$  parallel to the tangent vector  $\vec{r}'(t)$ . The **unit tangent vector**

$$\vec{T}(t) = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$$

**Theorem.** If  $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$ , then

$$\vec{r}'(t) = \langle f'(t), g'(t), h'(t) \rangle$$

**Example 4.** Find the derivative of the vector function  $\vec{r}(t) = \ln(4 - t^2)\vec{i} + \sqrt{1 + t}\vec{j} - 4e^{3t}\vec{k}$ .

**Example 5.** At what point do the curves  $\vec{r}_1(t) = \langle t, 1 - t, 3 + t^2 \rangle$  and  $\vec{r}_2(s) = \langle 3 - s, s - 2, s^2 \rangle$  intersect? Find their angle of intersection.

**Theorem.** Suppose  $\vec{u}$  and  $\vec{v}$  are differentiable vector functions,  $c$  is a scalar, and  $f$  is a real-valued function. Then

1.  $\frac{d}{dt}[\vec{u}(t) + \vec{v}(t)] = \vec{u}'(t) + \vec{v}'(t)$
2.  $\frac{d}{dt}[c\vec{u}(t)] = c\vec{u}'(t)$
3.  $\frac{d}{dt}[f(t)\vec{u}(t)] = f'(t)\vec{u}(t) + f(t)\vec{u}'(t)$
4.  $\frac{d}{dt}[\vec{u}(t) \cdot \vec{v}(t)] = \vec{u}'(t) \cdot \vec{v}(t) + \vec{u}(t) \cdot \vec{v}'(t)$
5.  $\frac{d}{dt}[\vec{u}(t) \times \vec{v}(t)] = \vec{u}'(t) \times \vec{v}(t) + \vec{u}(t) \times \vec{v}'(t)$
6.  $\frac{d}{dt}[\vec{u}(f(t))] = f'(t)\vec{u}'(t)$

**Example 6.** Show that if  $|\vec{r}'(t)| = c$ , where  $c$  is a constant, then  $\vec{r}'(t)$  is orthogonal to  $\vec{r}(t)$  for all  $t$ .

The **definite integral** of a continuous vector function  $\int_a^b \vec{r}(t) dt = \left\langle \int_a^b f(t) dt, \int_a^b g(t) dt, \int_a^b h(t) dt \right\rangle$

The Fundamental Theorem of Calculus for continuous vector functions says that

$$\int_a^b \vec{r}(t) dt = \vec{R}(t) \Big|_a^b = \vec{R}(b) - \vec{R}(a)$$

where  $\vec{R}$  is an antiderivative of  $\vec{r}$ . We use the notation  $\int \vec{r}(t) dt$  for indefinite integrals (antiderivatives).

**Example 7.** Find  $\vec{r}(t)$  if  $\vec{r}'(t) = \langle \sin t, -\cos t, 2t \rangle$  and  $\vec{r}(0) = \vec{i} + \vec{j} + 2\vec{k}$ .