

## Chapter 4. Linear Second Order Equations

Chapter 4.1 is skipped.

### Section 4.2 Linear Differential Operators

A **linear second order equation** is an equation that can be written in the form

$$a_2(x)\frac{d^2y}{dx^2} + a_1(x)\frac{dy}{dx} + a_0(x)y = b(x). \quad (1)$$

We will assume that  $a_0(x)$ ,  $a_1(x)$ ,  $a_2(x)$ ,  $b(x)$  are continuous functions of  $x$  on an interval  $I$ . When  $a_0$ ,  $a_1$ ,  $a_2$ ,  $b$  are constants, we say the equation has **constant coefficients**, otherwise it has **variable coefficients**.

For now, we are interested in those linear equations for which  $a_2(x)$  is never zero on  $I$ . In that case we can rewrite (1) in the **standard form**

$$\frac{d^2y}{dx^2} + p(x)\frac{dy}{dx} + q(x)y = g(x), \quad (2)$$

where  $p(x) = a_1(x)/a_2(x)$ ,  $q(x) = a_0(x)/a_2(x)$  and  $g(x) = b(x)/a_2(x)$  are continuous on  $I$ . Associated with equation (2) is the equation

$$y'' + p(x)y' + q(x)y = 0, \quad (3)$$

which is obtained from (2) by replacing  $g(x)$  with zero. We say that equation (2) is a **nonhomogeneous equation** and that (3) is the corresponding **homogeneous equation**.

Let's consider the expression on the left-hand side of equation (3),

$$y''(x) + p(x)y'(x) + q(x)y(x). \quad (4)$$

Given any function  $y$  with a continuous second derivative on the interval  $I$ , then (4) generates a new function

$$L[y] = y''(x) + p(x)y'(x) + q(x)y(x). \quad (5)$$

What we have done is to associate with each function  $y$  the function  $L[y]$ . This function  $L$  is defined *on a set of functions*. Its domain is the collection of functions with continuous second derivatives; its range consists of continuous functions; and the rule of correspondence is given by (5). We will call this mappings **operators**. Because  $L$  involves differentiation, we refer to  $L$  as a **differential operator**.

The image of a function  $t$  under the operator  $L$  is the function  $L[y]$ . If we want to evaluate this image function at some point  $x$ , we write  $L[y](x)$ .

**Example 1.** Let  $L[y](x) = x^2y''(x) - 3xy'(x) - 5y(x)$ . Compute

- (a)  $L[\cos x]$ ;                      (b)  $L[x^{-1}]$ ;  
(c)  $L[e^{rx}]$ ,  $r$  a constant.

SOLUTION.

- (a) If  $y = \cos x$ , then  $y' = -\sin x$  and  $y'' = -\cos x$ , so

$$L[y](x) = x^2y''(x) - 3xy'(x) - 5y(x) = x^2(-\cos x) - 3x(-\sin x) - 5\cos x = -(x^2 + 5)\cos x + 3x\sin x.$$

Thus,  $L$  maps the function  $\cos x$  to the function  $-(x^2 + 5)\cos x + 3x\sin x$ .

(b) If  $y = x^{-1}$ , then we similarly find

$$L[y](x) = x^2 y''(x) - 3xy'(x) - 5y(x) = x^2 \frac{2}{x^3} - 3x \left( -\frac{1}{x^2} \right) - 5 \frac{1}{x} = \frac{2}{x} + \frac{3}{x} - \frac{5}{x} = 0.$$

Thus,  $L$  maps the function  $x^{-1}$  to the zero function (or  $y = x^{-1}$  is the solution to the equation  $x^2 y''(x) - 3xy'(x) - 5y(x) = 0$ ).

(c) If  $y = e^{rx}$ ,

$$L[y](x) = x^2 y''(x) - 3xy'(x) - 5y(x) = x^2 r^2 e^{rx} - 3xr e^{rx} - 5e^{rx} = ((xr)^2 - 3xr - 5)e^{rx}.$$

Thus,  $L$  maps the function  $e^{rx}$  to the function  $((xr)^2 - 3xr - 5)e^{rx}$ .

The differential operator  $L$  defined by (5) has two very important properties.

**Lemma 1.** Let  $L[x] = y''(x) + p(x)y'(x) + q(x)y(x)$ . If  $y$ ,  $y_1$ , and  $y_2$  are any twice-differentiable functions on the interval  $I$  and if  $c$  is any constant, then

$$L[y_1 + y_2] = L[y_1] + L[y_2], \tag{6}$$

$$L[cy] = cL[y]. \tag{7}$$

**Proof.** On  $I$ , we have

$$\begin{aligned} L[y_1 + y_2] &= (y_1 + y_2)'' + p(x)(y_1 + y_2)' + q(x)(y_1 + y_2) = (y_1'' + y_2'') + p(x)(y_1' + y_2') + q(x)(y_1 + y_2) = \\ &= (y_1'' + p(x)y_1' + q(x)y_1) + (y_2'' + p(x)y_2' + q(x)y_2) = L[y_1] + L[y_2], \end{aligned}$$

which verifies property (6).

Similarly we can prove property (7).

Any operator that satisfied satisfies properties (6) and (7) for any constant  $c$  and any functions  $y$ ,  $y_1$ , and  $y_2$  in its domain is called a **linear operator** and we can say that " $L$  preserves linear combination". If (6) or (7) fails to hold, the operator is **nonlinear**.

Lemma 1 says that the operator  $L$ , defined by (5) is linear.

**Example 2.** Show that  $T$  defined by

$$T[y] = y'' + \{y'y^2\}^{1/3}$$

is a nonlinear.

**SOLUTION.** To demonstrate that  $T$  is nonlinear, it suffices to show that property (6) (or (7)) is *not always* satisfied. Let's try  $y_1(x) = x^2$  and  $y_2(x) = x^3$ . Since  $y_1'(x) = 2x$ ,  $y_1''(x) = 2$ ,  $y_2'(x) = 3x^2$ ,  $y_2''(x) = 6x$ ,

$$T[y_1] = 2 + \{2x \cdot x^4\}^{1/3} = 2 + \{2x^5\}^{1/3},$$

$$T[y_2] = 6x + \{3x^2 \cdot x^6\}^{1/3} = 6x + \{3x^8\}^{1/3},$$

$$T[y_1 + y_2] = 2 + 6x + \{(2x^5 + 3x^8)(x^2 + x^3)^2\}^{1/3} \neq 2 + \{2x^5\}^{1/3} + 6x + \{3x^7\}^{1/3},$$

so  $T[y_1] + T[y_2] \neq T[y_1 + y_2]$ , property (6) is violated. Hence,  $T$  is a nonlinear operator.

The linearity of the differential operator  $L$  in (5) can be used to prove the following theorem concerning homogeneous equations.

**Theorem 1 (linear combination of solutions).** Let  $y_1$  and  $y_2$  be solutions to the homogeneous equation (3). Then any linear combination  $C_1y_1 + C_2y_2$  of  $y_1$  and  $y_2$ , where  $C_1$  and  $C_2$  are constants, is also the solution to (3).

**Proof.** Since  $y_1$  and  $y_2$  are solutions to (3), then  $L[y_1] = 0$  and  $L[y_2] = 0$ . Using the linearity of  $L$ , we have

$$L[C_1y_1 + C_2y_2] = L[C_1y_1] + L[C_2y_2] = C_1L[y_1] + C_2L[y_2] = 0$$

for any  $C_1$  and  $C_2$ . Thus,  $C_1y_1 + C_2y_2$  is a solution to (3).

**Example 3.** Given that  $y_1(x) = e^{2x} \cos x$  and  $y_2(x) = e^{2x} \sin x$  are solutions to the homogeneous equation

$$y'' - 4y' + 5y = 0,$$

find solutions to this equation that satisfy the following initial conditions:

(a)  $y(0) = 2, y'(0) = 1.$

(b)  $y(\pi) = 4e^{2\pi}, y'(\pi) = 5e^{2\pi}.$

SOLUTION. As a consequence of T.1, any linear combination

$$y(x) = C_1e^{2x} \cos x + C_2e^{2x} \sin x$$

with  $C_1$  and  $C_2$  arbitrary constants, will be the solution also.

$$y'(x) = 2C_1e^{2x} \cos x - C_1e^{2x} \sin x + 2C_2e^{2x} \sin x + C_2e^{2x} \cos x =$$

$$(2C_1 + C_2)e^{2x} \cos x + (2C_2 - C_1)e^{2x} \sin x.$$

(a)

$$y(0) = C_1(1)(1) + C_2(1)(0) = C_1 = 2,$$

$$y'(0) = (2C_1 + C_2)(1) + (2C_2 - C_1)(0) = 2C_1 + C_2 = 1.$$

Since  $C_2 = 1 - 2C_1$  and  $C_1 = 2$ ,  $C_2 = -3$ . Hence, the solution to the given initial value problem is

$$y(x) = 2e^{2x} \cos x - 3e^{2x} \sin x.$$

(b)

$$y(\pi) = C_1 e^{2\pi}(-1) + C_2 e^{2\pi}(0) = -C_1 e^{2\pi} = 4e^{2\pi},$$

so,  $C_1 = -4$ .

$$y'(\pi) = (2C_1 + C_2)e^{2\pi}(-1) + (2C_2 - C_1)e^{2\pi}(0) = -(2C_1 + C_2)e^{2\pi} = 5e^{2\pi},$$

so,  $2C_1 + C_2 = -5$ . Since  $C_2 = -5 - 2C_1$  and  $C_1 = -4$ ,  $C_2 = 3$ . Hence, the solution to the given initial value problem is

$$y(x) = -4e^{2x} \cos x + 3e^{2x} \sin x.$$