## Chapter 1. Introduction.

- Equation that contains some derivatives of an unknown function is called a **differential** equation.
- If an equation involves the derivative of one variable with respect to another, then the former is called a **dependent variable** and the latter is called an **independent variable**.
- A differential equation involving only ordinary derivatives with respect to a single variable is called an **ordinary differential equations** or ODE. A differential equation involving partial derivatives with respect to more then one variable is a **partial differential equations** or PDE.
- The **order** of a differential equation is the order of the highest-order derivatives present in equation.
- An ODE is **linear** if it has format

$$a_n(x)\frac{d^n y}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + a_1(x)\frac{dy}{dx} + a_0(x)y = F(x),$$

where  $a_n(x)$ ,  $a_{n-1}(x)$ ,..., $a_0(x)$  and F(x) depend only on variable x. If an ODE is not linear, then we call it **nonlinear**.

**Example 1.** For each of the differential equations indicate whether it is linear or nonlinear.

1. 
$$\ln(x)\frac{d^2y}{dx^2} + 3e^x\frac{dy}{dx} - y\sin x = 0$$
  
2.  $2y'' - 3y^2 = e^x$   
3.  $\frac{d^3y}{dx^3} + (x^2 - 1)y + \cos x = 0$   
4.  $y'' - \sin(x + y)y' + (x^2 + 1)y = 0$ 

5. 
$$y'' - e^{xy} = \cos(2x + y)$$

A general form for an *n*th-order equation with variable x and unknown function y = y(x) can be expressed as

$$F\left(x, y, \frac{dy}{dx}, \cdots, \frac{d^n y}{dx^n}\right) = 0,$$
(1)

where F is a function that depends on x, y, and the derivatives of y up to the order n. We assume that the equation holds for all x in an open interval I (a < x < b, where a or b could be infinite).

$$\frac{d^n y}{dx^n} = f\left(x, y, \frac{dy}{dx}, \cdots, \frac{d^{n-1}y}{dx^{n-1}}\right) = 0.$$
(2)

- A function  $\varphi(x)$  that when substituted by y in the equation satisfies the equation for all x in the interval I is called a **solution** to the equation on I.
- By an **initial value problem** for an *n*th-order differential equation

$$F\left(x, y, \frac{dy}{dx}, \cdots, \frac{d^n y}{dx^n}\right) = 0$$

we mean: Find a solution to the differential equation on an interval I that satisfies at  $x_0$  the n initial conditions:

$$y(x_0) = y_0, \quad \frac{dy}{dx}(x_0) = y_1, \dots, \frac{d^{n-1}y}{dx^{n-1}}(x_0) = y_{n-1},$$

where  $x_0 \in I$  and  $y_0, y_1, \dots, y_{n-1}$  are given constants.

• In case of a first-order equation  $F\left(x, y, \frac{dy}{dx}\right)$ , the initial conditions reduce to the single requirement

$$y(x_0) = y_0$$

• In case of a second-order equation, the initial conditions have the form

$$y(x_0) = y_0, \qquad \qquad \frac{dy}{dx}(x_0) = y_1.$$

## **Direction Fields.**

One technique that is useful in graphing the solutions to a first-order differential equation is to sketch the direction field for the equation. To describe this method, we need to make a general observation.

Namely, a first-order equation

$$\frac{dy}{dx} = f(x, y)$$

specifies a slope at each point in the xy-plane where f is defined.

A plot of short line segments drawn at various points in the *xy*-plane showing the slope of the solution curve there is called a **direction field** for the differential equation. Because the direction field gives the "flow of solutions", it facilitates the drawing of any particular solution (such as the solution to an initial value problem).

## Example 2.

- 1. Sketch a direction field for y' = t + y
- 2. Using the direction field, describe the behavior of the solution as  $t \to \pm \infty$ .

```
We can get directional field using MatLab.
>>[t,y]=meshgrid(-3:0.2:2, -1:0.2:5);
>> s=t+y;
>> quiver(t,y,ones(size(s)), s), axis tight
```

```
All array must have the same size, therefore we do
>>[t,y]=meshgrid(-3:0.2:2, -1:0.2:5);
>> s=t+y;
>> l=sqrt(1+s. < 2);
>> quiver(t,y,1./l,s./l,0.5), axis tight
To graph solutions, we do
>>[t,y]=meshgrid(-3:0.2:2, -1:0.2:5);
>> s=t+y;
>> l=sqrt(1+s. ^ 2);
>> quiver(t,y,1./l,s./l,0.5), axis tight
>> f=@(t,y)t+y;
>> hold on
>> for y0=-3:1:2
[ts,ys]=ode45(f,[-3,2],y0); plot(ts,ys)
end
>> hold off
```

## Example 3.

- 1. Sketch a direction field for  $y' = t^2 y$
- 2. Using the direction field, describe the behavior of the solution as  $t \to \pm \infty$ .