## 13.1: Vector Functions and Space Curves

A vector function is a function that takes one or more variables and returns a vector. Let  $\mathbf{r}(t)$  be a vector function whose range is a set of 3-dimensional vectors:

$$\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k},$$

where x(t), y(t), z(t) are functions of one variable and they are called the **component functions**.

A vector function  $\underline{\mathbf{r}(t)}$  is *continuous* if and only if its component functions x(t), y(t), z(t) are continuous.

Space curve is given by parametric equations:

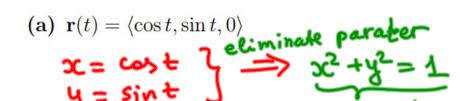
$$C = \{(x, y, z) | x = x(t), y = y(t), z = z(t), t \text{ in } I\},\$$

where I is an interval and t is a parameter.

FACT: Any continuous vector-function  $\mathbf{r}(t)$  defines a space curve C that is traced out by the tip of the moving vector  $\mathbf{r}(t)$ .

Any parametric curve has a direction of motion given by increasing of parameter.

EXAMPLE 1. Describe the curve defined by the vector function (indicate direction of motion):

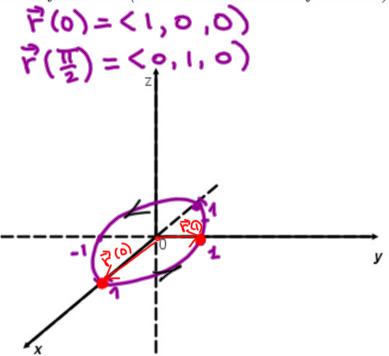


the xy plane

We get line of intersection

between cylinder x² +y²=1

and the xy-plane (z=0)

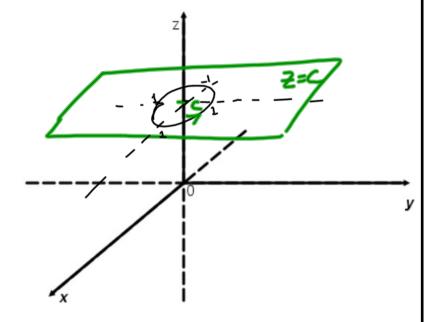


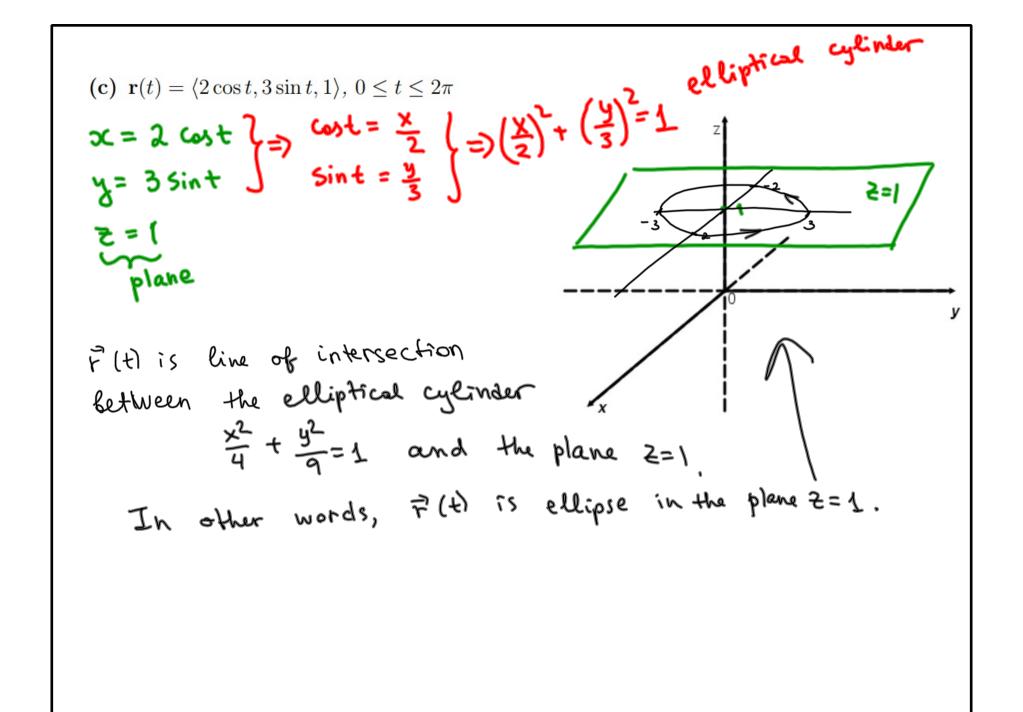
**(b)**  $\mathbf{r}(t) = \langle \cos at, \sin at, c \rangle$  where a and c are positive constants.

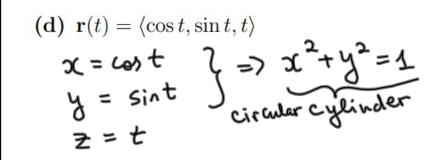
$$x = cos at$$
 $y = sin at$ 
 $z^2 + y^2 = 1$ 
 $z = c$ 
 $z = c$ 
 $z = c$ 
 $z = c$ 

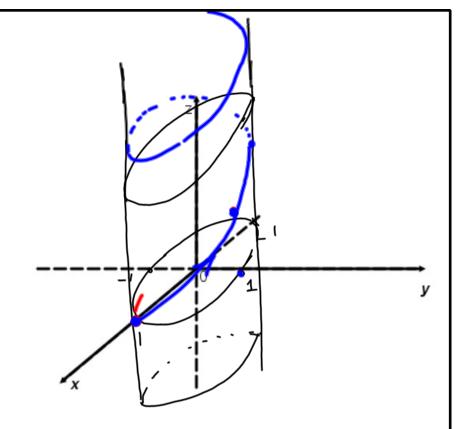
circle with radius 1 centered at (0,0, c) in the plane z=c

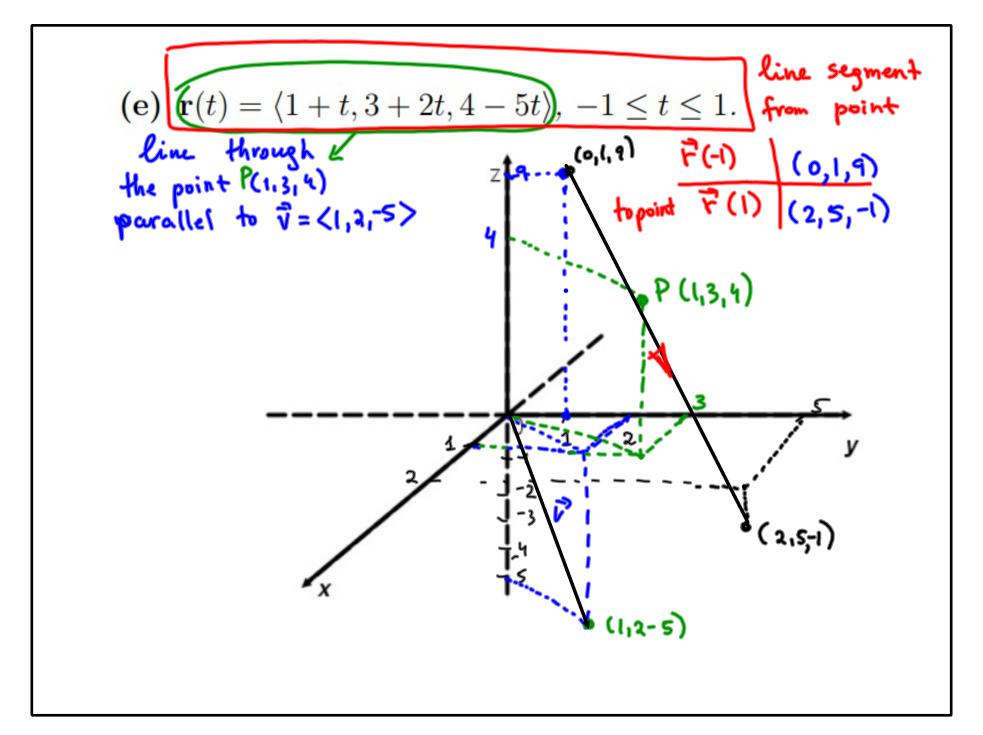
$$\vec{F}(0) = \langle 1, 0, C \rangle$$
  
 $\vec{F}(\frac{\pi}{2a}) = \langle 0, 1, C \rangle$ 











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EXAMPLE 2. Show that the the curve given by  $\mathbf{r}(t) = \left\langle \sin t, 2\cos t, \sqrt{3}\sin t \right\rangle$ lies on both a plane and a sphere. Then conclude that its graph is a circle and find its radius.  $x^2 + y^2 + 2^{(0,008(3))}$  =  $\sin^2 t + 4 \cos^2 t + 3 \sin^2 t$ x = sint (1) = 4 sin2t + 4 cos2t = 4 (sin2t + cos2t) y= 2 cost (2) Z = \(\frac{13}{3}\) Sin + (3) = 4.1 = 4 So, the curve belongs to the sphere  $x^2 + y^2 + z^2 = 4$ . that Z=13x and this equation of plane through origin. Thus the given curve belongs to this plane as well. so, the given curve is a line of intersection between sphere centered at origin and with radius 2 and plane through the origin. Thus the given curve is a circle centered at (0,0,0) with radius 2

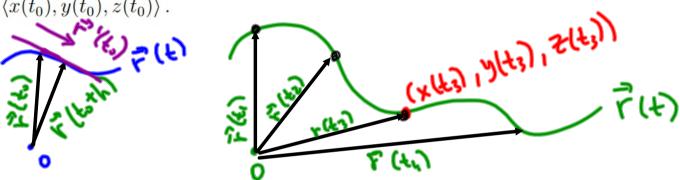
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## 13.2 Derivatives of Vector Functions

The derivative  $\mathbf{r}'$  of a vector function  $\mathbf{r}$  is defined just as for a real-valued function:

$$\frac{\mathrm{d}\mathbf{r}(t_0)}{\mathrm{d}t} = \mathbf{r}'(t_0) = \lim_{h \to 0} \frac{\mathbf{r}(t_0 + h) - \mathbf{r}(t_0)}{h}$$

if the limit exists. The derivative  $\mathbf{r}'(t_0)$  is the tangent vector to the curve  $\mathbf{r}(t)$  at the point  $\mathbf{r}(t_0) = \langle x(t_0), y(t_0), z(t_0) \rangle$ .



THEOREM 3. If the functions x(t), y(t), z(t) are differentiable, then

$$\mathbf{r}'(t) = \langle x'(t), y'(t), z'(t) \rangle = x'(t)\mathbf{i} + y'(t)\mathbf{j} + z'(t)\mathbf{k}.$$

EXAMPLE 4. Given  $\mathbf{r}(t) = (1+t)^2 \mathbf{i} + e^t \mathbf{j} + \sin 3t \mathbf{k}$ .

(a) Find 
$$\mathbf{r}'(t)$$
 $\vec{r}'(t) = \langle ((1+t)^2)^1, (e^t)^1, (\sin 3t)^1 \rangle$ 
 $= \langle 2(1+t), e^t, 3\cos 3t \rangle$ 
qiven by  $\vec{r}(t)$ 

(b) Find a tangent vector to the curve at t = 0.

(c) Find a tangent line to the curve at t = 0. First find position of time t = 0:  $F'(0) = \langle (0t)^2, e^0, \sin(3.0) \rangle = \langle 1, 1, 0 \rangle$ So, the tangent passes through the point (1, 1, 0) and parallel to the vector  $\langle 2, 1, 3 \rangle$  (see part (b))

(c) Find a tangent line to the curve at the point (1,1,0). Find to such that  $P(t) = \langle 1,1,0 \rangle$ .

Then calculate  $P(t_0) = \langle 1,1,0 \rangle$ .