9. Solutions of linear homogeneous equations of second order. The Wronskian (section 3.2).

1. **Second order ODE:**

$$y'' = f(t, y, y')$$

   where f is a function whose domain is in $\mathbb{R}^3$. A solution of such an equation is a function $y = y(t)$, twice differentiable in some interval I, s.t. for all t in I

$$y''(t) = f(t, y(t), y'(t)).$$

2. By Newton's Second Law $F = ma$. We know that acceleration $a(t)$ is the second derivative of position $x(t)$, which yields

$$x'' = \frac{1}{m} F(x, x').$$

3. Find general solution of $y'' = 0$.

4. Reduction to the first order ODE by a substitution:

- Particular case $y'' = f(t, y')$ use the substitution $u = y'$.
- General case $y'' = f(t, y, y')$ use the substitution $x_1 = y, \quad x_2 = y_1'$.

5. By analogy with the existence and uniqueness theorem for a single first order ODE we have

THEOREM 1. *If* f, $\dfrac{\partial f}{\partial x_1}$ *and,* $\dfrac{\partial f}{\partial x_2}$ *are continuous in a region*

$$R = \{\alpha < t < \beta, \quad \alpha_1 < x_1 < \beta_1, \quad \alpha_2 < x_2 < \beta_2\}$$

then there exists a unique solution through a point (t_0, y_0, v_0) *in* R *(equivalently, there is an interval* $t_0 - h < t < t_0 + h$ *in which there exists a unique solution of the IVP*
$y'' = f(t, y, y'), \quad y(t_0) = y_0, \quad y'(t_0) = v_0$*.)*

6. Second order **linear** ODE:

$$y'' + p(t)y' + q(t)y = g(t)$$

or

$$y'' = -p(t)y' - q(t)y + g(t)$$

where $p, q,$ and g are continuous on an interval $I = (\alpha, \beta)$

7. By analogy with the existence and uniqueness theorem for a linear first order ODE we have

THEOREM 2. *If the functions $p(t), q(t)$ and $g(t)$ are continuous on the interval then for any $t = t_0$ on I, there is a* **unique** *solution $y = y(t)$ of the IVP*

$$y'' + p(t)y' + q(t)y = g(t), \quad y(t_0) = y_0, \quad y'(t_0) = v_0. \tag{1}$$

Linear HOMOGENEOUS ODE of second order

8. Question: Can the function $y = \sin(t^2)$ be a solution on the interval $(-1, 1)$ of a second order linear homogeneous equation with continuous coefficients?

9. Consider a linear homogeneous ODE

$$y'' + p(t)y' + q(t)y = 0 \tag{2}$$

with coefficients p and q continuous in an interval I.

10. **Superposition Principle**

- Sum $y_1(t) + y_2(t)$ of any two solutions $y_1(t)$ and $y_2(t)$ of (2) is itself a solution.

- A scalar multiple $Cy(t)$ of any solution $y(t)$ of (2) is itself a solution.

COROLLARY 3. *Any* `linear combination` $C_1y_1(t) + C_2y_2(t)$ *of any two solutions* $y_1(t)$ *and* $y_2(t)$ *of (2) is itself a solution.*

11. `Why Superposition Principle is important?` Once two solutions of a linear homogeneous equation are known, a whole class of solutions is generated by linear combinations of these two.

12. **WRONSKIAN** of the functions $y_1(t)$ and $y_2(t)$:

$$W(y_1, y_2)(t) = \begin{vmatrix} y_1(t) & y_2(t) \\ y_1'(t) & y_2'(t) \end{vmatrix}$$

13. Suppose that $y_1(t)$ and $y_2(t)$ are two differentiable solutions of (2) in the interval I such that $W(y_1, y_2)(t) \neq 0$ somewhere in I, then every solution is a linear combination of $y_1(t)$ and $y_2(t)$.

In other words, the family of solutions $y(t) = C_1 y_1(t) + C_2 y_2(t)$ with arbitrary coefficients C_1 and C_2 includes every solution of (2) if and only if there is a points t_0 where $W(y_1, y_2)$ is not zero. In this case the pair $(y_1(t), y_2(t))$ is called the **fundamental set** of solutions of (2).

REMARK 4. Wronskian $W(y_1, y_2)(t)$ (of any two solutions $y_1(t)$ and $y_2(t)$ of (2))either is zero for all t or else is never zero.

14. Confirm that $\sin x$ and $\cos x$ are solutions of $y'' + y = 0$. Then solve the IVP

$$y'' + y = 0, \quad y(1) = 0, \quad y'(1) = -5$$

Appendix: Facts from Algebra

1. • FACT 1: **Cramer's Rule** for solving the system of equations

$$a_1x + b_1y = c_1$$
$$a_1x + b_2y = c_2$$

The rule says is that if the `determinant of the coefficient matrix is not zero`, i.e.

$$\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix} \neq 0,$$

then the system has a unique solution (x, y) given by

$$x = \frac{\begin{vmatrix} c_1 & b_1 \\ c_2 & b_2 \end{vmatrix}}{\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}}, \qquad y = \frac{\begin{vmatrix} a_1 & c_1 \\ a_2 & c_2 \end{vmatrix}}{\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}}$$

- FACT 2: If determinant of the coefficient matrix is zero then either there is no solution, or there are infinitely many solutions.
- FACT 3. The homogeneous system of linear equations

$$a_1x + b_1y = 0$$
$$a_1x + b_2y = 0$$

always has the "trivial" solution $(x, y) = (0, 0)$. By Cramer's rule this is the only solution if the determinant of the coefficient matrix is not zero.

- FACT 4: If determinant of the coefficient matrix of homogeneous system of linear equations is zero then there are infinitely many nontrivial solutions $(x, y) \neq (0, 0)$.

2. Use Facts 1-4 to determine if each the following systems of linear equations has one solution, no solutio infinitely many solutions. Then find the solution/s (if any).

(a) $$\begin{aligned} 2x + 3y &= 5 \\ x - y &= 4 \end{aligned}$$

(b)
$$\begin{aligned} 2x - 2y &= 4 \\ x - y &= 7 \end{aligned}$$

(c)
$$\begin{aligned} 2x - 2y &= 0 \\ 3x + 3y &= 0 \end{aligned}$$

(d)
$$\begin{aligned} 2x - 2y &= 0 \\ 3x - 3y &= 0 \end{aligned}$$