

11.6: Vector Functions and Space Curves

A vector function is a function that takes one or more variables and returns a vector. Let $\mathbf{r}(t)$ be a vector function whose range is a set of 3-dimensional vectors:

$$\mathbf{r}(t) = \langle x(t), y(t), z(t) \rangle = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k},$$

$$\mathbb{R} \rightarrow \mathbb{R}^3$$

where $x(t), y(t), z(t)$ are functions of one variable and they are called the **component functions**.

A vector function $\mathbf{r}(t)$ is *continuous* if and only if its component functions $x(t), y(t), z(t)$ are continuous.

EXAMPLE 1. Given

$$\mathbf{r}(t) = \langle \overset{=x(t)}{t \ln(t+1)}, \overset{=y(t)}{t^2 \sin t}, \overset{=z(t)}{e^t} \rangle.$$

(a) Find the domain of $\mathbf{r}(t)$.

$$\left. \begin{array}{l} D(x(t)) = \{t+1 > 0\} = \{t > -1\} \\ D(y(t)) = D(z(t)) = \mathbb{R} \end{array} \right\} D(\vec{r}(t)) = \{t > -1\} \text{ or } (-1, \infty)$$

(b) Find all t where $\mathbf{r}(t)$ is continuous.

$$(-1, \infty)$$

Space curve is given by parametric equations:

$$C = \{(x, y, z) | x = x(t), y = y(t), z = z(t), t \text{ in } I\},$$

$$\vec{r}(t) = \langle x(t), y(t), z(t) \rangle$$

where I is an interval and t is a parameter.

FACT: Any continuous vector-function $\vec{r}(t)$ defines a space curve C that is traced out by the tip of the moving vector $\vec{r}(t)$.

Any parametric curve has a **direction of motion** given by increasing of parameter.

$$t_1 < t_2 \Rightarrow \text{Find } \vec{r}(t_1), \vec{r}(t_2)$$



EXAMPLE 2. Describe the curve defined by the vector function (indicate direction of motion):

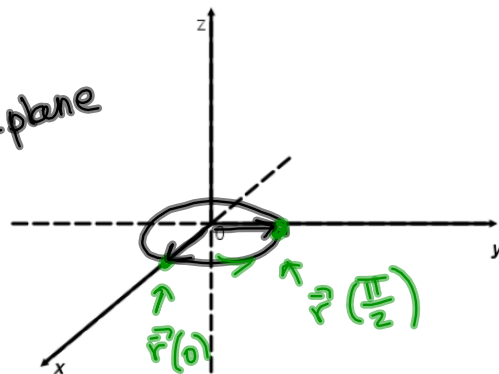
(a) $\vec{r}(t) = \langle \cos t, \sin t, 0 \rangle$

$$\left. \begin{array}{l} x = \cos t \\ y = \sin t \\ z = 0 \end{array} \right\} \Rightarrow \begin{array}{l} x^2 + y^2 = 1 \\ z = 0 \end{array}$$

circle in the xy -plane

$$\vec{r}(0) = \langle 1, 0, 0 \rangle$$

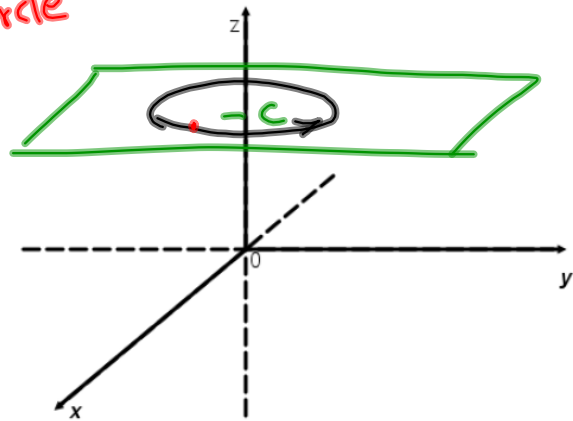
$$\vec{r}\left(\frac{\pi}{2}\right) = \langle 0, 1, 0 \rangle$$



(b) $\mathbf{r}(t) = \langle \cos at, \sin at, c \rangle$ where a and c are positive constants.

$$\left. \begin{array}{l} x = \cos at \\ y = \sin at \\ z = c \end{array} \right\} \Rightarrow \begin{array}{l} x^2 + y^2 = 1 \\ z = c \end{array}$$

\downarrow unit circle
 in the plane
 $z = c$

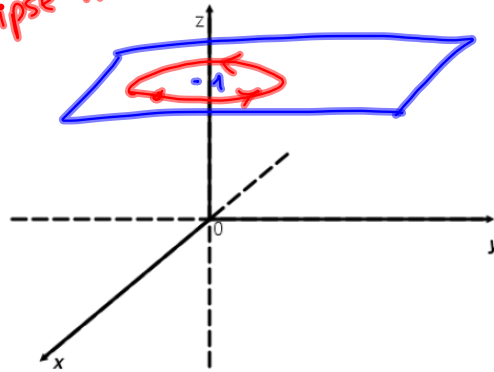


parameter domain

(c) $\mathbf{r}(t) = \langle 2 \cos t, 3 \sin t, 1 \rangle, 0 \leq t \leq 2\pi$

$$\left. \begin{array}{l} x = 2 \cos t \\ y = 3 \sin t \\ z = 1 \end{array} \right\} \Rightarrow \begin{array}{l} \left(\frac{x}{2}\right)^2 + \left(\frac{y}{3}\right)^2 = 1 \\ z = 1 \end{array}$$

ellipse in the plane $z=1$

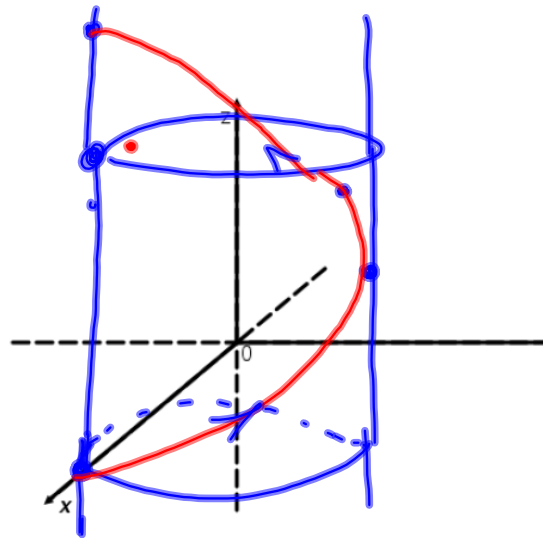


(d) $r(t) = \langle \cos t, \sin t, t \rangle$

$x = \cos t$
 $y = \sin t$

$\Rightarrow x^2 + y^2 = 1$

$z = t$



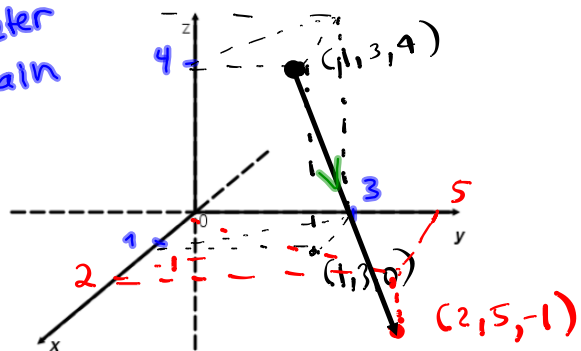
(e) $r(t) = \langle 1+t, 3+2t, 4-5t \rangle, 0 \leq t \leq 1$.

line segment

parameter domain

$\vec{r}(0) = \langle 1, 3, 4 \rangle$

$\vec{r}(1) = \langle 2, 5, -1 \rangle$



EXAMPLE 3. Show that the curve given by

$$\mathbf{r}(t) = \langle \sin t, 2 \cos t, \sqrt{3} \sin t \rangle$$

lies on both a plane and a sphere. Then conclude that its graph is a circle and find its radius.

$$x = \sin t$$

$$y = 2 \cos t$$

$$z = \sqrt{3} \sin t$$

$$\Rightarrow z = \sqrt{3} \underbrace{\sin t}_x = \sqrt{3}x$$

$$\Rightarrow \boxed{z = \sqrt{3}x}$$

 plane
 through
 the origin

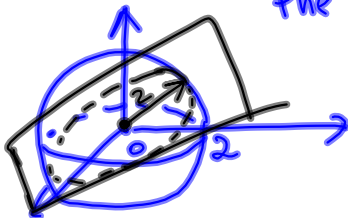
$$x^2 + y^2 + z^2 = (\sin t)^2 + (2 \cos t)^2 + (\sqrt{3} \sin t)^2$$

$$= \sin^2 t + 4 \cos^2 t + 3 \sin^2 t$$

$$= 4 \sin^2 t + 4 \cos^2 t = 4$$

$$\boxed{x^2 + y^2 + z^2 = 4} \text{ sphere centered at origin with radius } 2$$

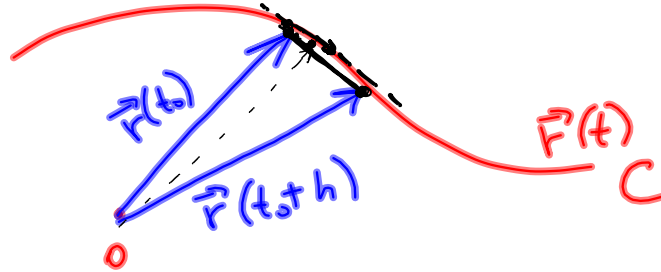
the radius of this circle of intersection is 2



Derivatives: The derivative \mathbf{r}' of a vector function \mathbf{r} is defined just as for a real-valued function:

$$\frac{d\mathbf{r}(t_0)}{dt} = \mathbf{r}'(t_0) = \lim_{h \rightarrow 0} \frac{\mathbf{r}(t_0 + h) - \mathbf{r}(t_0)}{h}$$

if the limit exists. The derivative $\mathbf{r}'(t_0)$ is the tangent vector to the curve $\mathbf{r}(t)$ at the point $\mathbf{r}(t_0) = \langle x(t_0), y(t_0), z(t_0) \rangle$.



THEOREM 4. If the functions $x(t), y(t), z(t)$ are differentiable, then

$$\mathbf{r}'(t) = \langle x'(t), y'(t), z'(t) \rangle = x'(t)\mathbf{i} + y'(t)\mathbf{j} + z'(t)\mathbf{k}.$$

EXAMPLE 5. Given $\mathbf{r}(t) = (1+t)^2\mathbf{i} + e^t\mathbf{j} + \sin 3t\mathbf{k}$.

(a) Find $\mathbf{r}'(t)$

$$\mathbf{r}'(t) = \left\langle \frac{d}{dt}(1+t)^2, \frac{d}{dt}(e^t), \frac{d}{dt}(\sin 3t) \right\rangle = \langle 2(1+t), e^t, 3\cos 3t \rangle$$

(b) Find a tangent vector to the curve at $t=0$.

$$\vec{v} = \mathbf{r}'(0) = \langle 2, 1, 3 \rangle$$

(c) Find a tangent line to the curve at $t=0$.

$$\begin{aligned} x &= x_0 + at \\ y &= y_0 + bt \\ z &= z_0 + ct \end{aligned}$$

$\vec{r}(0)$ $\vec{v} = \mathbf{r}'(0)$

$$\vec{r}(0) = \langle 1, 1, 0 \rangle$$

$$x = 1 + 2t$$

$$y = 1 + 1t$$

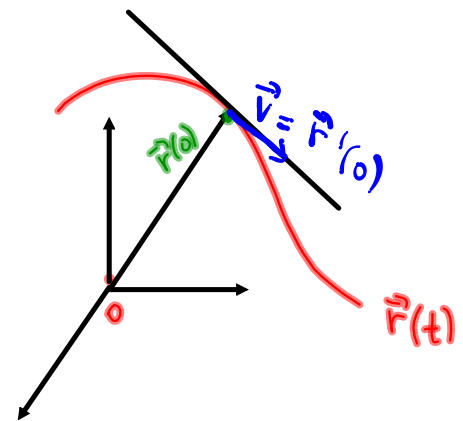
$$z = 0 + 3t$$

\Rightarrow

$$x = 1 + 2t$$

$$y = 1 + t$$

$$z = 3t$$



(c) Find a tangent line to the curve at the point $\langle 1, 1, 0 \rangle$.

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