



20: Impulse Function (section 6.5)

- In applications (mechanical systems, electrical circuits etc) one encounters functions (external force) of large magnitude that acts only for a very short period of time. To deal with violent forces of short duration the so called delta function is used. This function was introduces by Paul Dirac.
- 2. If a force F(t) acts on a body of mass m on the time interval $[t_0, t_1]$, then the impulse due to F is defined by the integral

defined by the integral impulse
$$= \int_{t_0}^{t_1} F(t) dt = \int_{t_0}^{t_1} ma(t) dt = \int_{t_0}^{t_1} dv(t) dt = mv(t_1) - mv(t_0)$$

3. The impulse equals the change in momentum.

When a hammer strikes an object, it transfers momentum to the object. This change in momentum takes place over a very short period of time. The change in momentum (=the impulse) is the area under the curve defined by F(t)

the total impulse of the force
$$F(t) = \int_{-\infty}^{\infty} F(t) dt$$

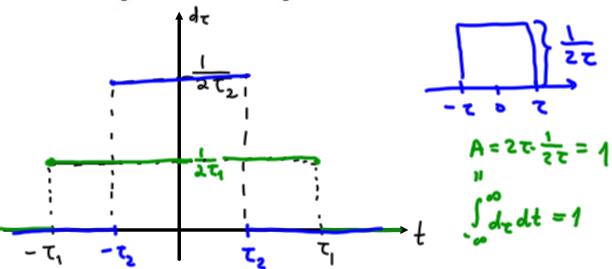
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4. Consider a family of piecewise functions (forces)

$$d_{\tau} = \begin{cases} \frac{1}{2\tau}, & \text{if } |t| \geq \tau \\ 0, & \text{if } |t| \geq \tau. \end{cases} - \tau < t < \tau$$

$$t > \tau, t \leq \tau$$

Then all forces d_{τ} have the total impulse which is equal 1.



5. Dirac DELTA Function: In practice it is convenient to work with another type of unit impulse, an idealized unit impulse force that concentrated at t = 0:

$$\lim_{\tau \to 0} d_{\tau}(t) = \delta(t).$$

6. Definition The Dirac Delta Function, $\delta(t)$, is characterized by the following 2 properties:

(a)
$$\delta(t) = 0$$
 for all $t \neq 0$

(b) $\int_{-\infty}^{\infty} \delta(t) f(t) dt = f(0)$ for any f(t) continuous on an open interval containing t = 0.

Note that $\delta\text{-function}$ does not behave like an ordinary function.

7. A unit impulse concentrated at $t = t_0$ is denoted by $\delta(t - t_0)$ and

$$\int_{-\infty}^{\infty} \delta(t - t_0) f(t) dt = f(t_0), \quad t \neq t_0.$$

8. Laplace Transform of *delta*-function:

For
$$t_0 \ge 0$$

$$\mathcal{L}\left\{\delta(t)\right\} = 1$$

$$\mathcal{L}\left\{\delta(t-t_0)\right\} = e^{-st_0}$$

$$\mathcal{L}\left\{\delta(t)\right\} = \int_0^{+\infty} \delta(t) e^{-st} dt = 0$$

$$= \int_{-\infty}^{+\infty} f(t) e^{-st} dt = f(0) = e^{-s \cdot 0} = e^{0} = 1$$

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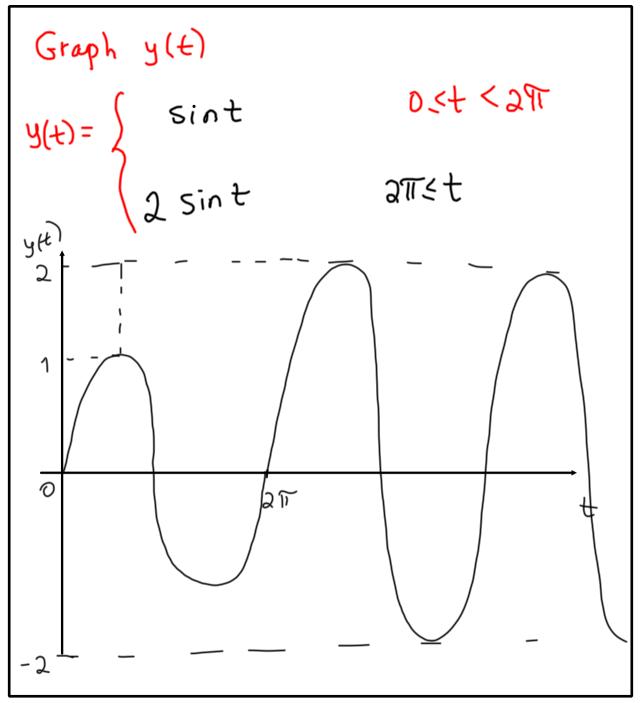
11. Remark:

$$\int_{-\infty}^{t} \delta(t - t_0) dt = \begin{cases} 0, & t < t_0 \\ 1, & t \ge t_0 \end{cases} = u_{t_0}(t).$$

In other words, derivative of unit step function is *delta*-function.

9. Solve the given IVP and sketch the graph of the solution: $y'' + y = \delta(t - 2\pi), \quad y(0) = 0, \quad y'(0) = 1.$ $\frac{1}{Y(s)(s^2+1)-1} = e^{-a\pi s} \Rightarrow Y(s) = (e^{-a\pi s}+1) \cdot \frac{1}{s^2+1}$ Y(5) = e G(5) + G(5) $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ $y(t) = \int_{-1}^{1} \left\{ e^{2\pi S} G(s) \right\} + \int_{-1}^{1} \left\{ G(s) \right\}$ g(+) = sin +

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