# MATH 311

Topics in Applied Mathematics I

# Lecture 6: Diagonal matrices. Inverse matrix.

# **Diagonal matrices**

If  $A = (a_{ij})$  is a square matrix, then the entries  $a_{ii}$  are called **diagonal entries**. A square matrix is called **diagonal** if all non-diagonal entries are zeros.

Example. 
$$\begin{pmatrix} 7 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$
, denoted diag $(7, 1, 2)$ .

Let 
$$A = \operatorname{diag}(s_1, s_2, ..., s_n)$$
,  $B = \operatorname{diag}(t_1, t_2, ..., t_n)$ .  
Then  $A + B = \operatorname{diag}(s_1 + t_1, s_2 + t_2, ..., s_n + t_n)$ ,  $rA = \operatorname{diag}(rs_1, rs_2, ..., rs_n)$ .

Example.

$$\begin{pmatrix} 7 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 3 \end{pmatrix} = \begin{pmatrix} -7 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 6 \end{pmatrix}$$

**Theorem** Let 
$$A = \operatorname{diag}(s_1, s_2, \ldots, s_n)$$
,  $B = \operatorname{diag}(t_1, t_2, \ldots, t_n)$ .

Then 
$$A + B = \operatorname{diag}(s_1 + t_1, s_2 + t_2, \dots, s_n + t_n),$$
  
 $rA = \operatorname{diag}(rs_1, rs_2, \dots, rs_n).$   
 $AB = \operatorname{diag}(s_1t_1, s_2t_2, \dots, s_nt_n).$ 

In particular, diagonal matrices always commute (i.e., AB = BA).

#### Example.

$$\begin{pmatrix} 7 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = \begin{pmatrix} 7a_{11} & 7a_{12} & 7a_{13} \\ a_{21} & a_{22} & a_{23} \\ 2a_{31} & 2a_{32} & 2a_{33} \end{pmatrix}$$

**Theorem** Let  $D = \operatorname{diag}(d_1, d_2, \dots, d_m)$  and A be an  $m \times n$  matrix. Then the matrix DA is obtained from A by multiplying the ith row by  $d_i$  for  $i = 1, 2, \dots, m$ :

$$A = \begin{pmatrix} \mathbf{v}_1 \\ \mathbf{v}_2 \\ \vdots \\ \mathbf{v}_m \end{pmatrix} \implies DA = \begin{pmatrix} d_1 \mathbf{v}_1 \\ d_2 \mathbf{v}_2 \\ \vdots \\ d_m \mathbf{v}_m \end{pmatrix}$$

#### Example.

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \begin{pmatrix} 7 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} = \begin{pmatrix} 7a_{11} & a_{12} & 2a_{13} \\ 7a_{21} & a_{22} & 2a_{23} \\ 7a_{31} & a_{32} & 2a_{33} \end{pmatrix}$$

**Theorem** Let  $D = \operatorname{diag}(d_1, d_2, \ldots, d_n)$  and A be an  $m \times n$  matrix. Then the matrix AD is obtained from A by multiplying the ith column by  $d_i$  for  $i = 1, 2, \ldots, n$ :

$$A = (\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_n)$$

$$\implies AD = (d_1\mathbf{w}_1, d_2\mathbf{w}_2, \dots, d_n\mathbf{w}_n)$$

#### **Identity** matrix

Definition. The **identity matrix** (or **unit matrix**) is a diagonal matrix with all diagonal entries equal to 1. The  $n \times n$  identity matrix is denoted  $I_n$  or simply I.

$$I_1=(1), \quad I_2=egin{pmatrix} 1 & 0 \ 0 & 1 \end{pmatrix}, \quad I_3=egin{pmatrix} 1 & 0 & 0 \ 0 & 1 & 0 \ 0 & 0 & 1 \end{pmatrix}.$$

In general, 
$$I = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & & 1 \end{pmatrix}$$
.

**Theorem.** Let A be an arbitrary  $m \times n$  matrix. Then  $I_m A = AI_n = A$ .

#### **Inverse** matrix

Let  $\mathcal{M}_n(\mathbb{R})$  denote the set of all  $n \times n$  matrices with real entries. We can **add**, **subtract**, and **multiply** elements of  $\mathcal{M}_n(\mathbb{R})$ . What about **division**?

Definition. Let  $A \in \mathcal{M}_n(\mathbb{R})$ . Suppose there exists an  $n \times n$  matrix B such that

$$AB = BA = I_n$$
.

Then the matrix A is called **invertible** and B is called the **inverse** of A (denoted  $A^{-1}$ ).

A non-invertible square matrix is called **singular**.

$$AA^{-1} = A^{-1}A = I$$

#### **Examples**

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$
,  $B = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}$ ,  $C = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$ .

$$BA = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix},$$

$$C^2 = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Thus  $A^{-1} = B$ ,  $B^{-1} = A$ , and  $C^{-1} = C$ .

 $AB = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix},$ 

# Basic properties of inverse matrices

- If  $B = A^{-1}$  then  $A = B^{-1}$ . In other words, if A is invertible, so is  $A^{-1}$ , and  $A = (A^{-1})^{-1}$ .
- The inverse matrix (if it exists) is unique. Moreover, if AB = CA = I for some  $n \times n$  matrices B and C, then  $B = C = A^{-1}$ .

Indeed, 
$$B = IB = (CA)B = C(AB) = CI = C$$
.

• If  $n \times n$  matrices A and B are invertible, so is AB, and  $(AB)^{-1} = B^{-1}A^{-1}$ .

$$(B^{-1}A^{-1})(AB) = B^{-1}(A^{-1}A)B = B^{-1}IB = B^{-1}B = I,$$
  
 $(AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = AIA^{-1} = AA^{-1} = I.$ 

• Similarly,  $(A_1A_2...A_k)^{-1} = A_k^{-1}...A_2^{-1}A_1^{-1}$ .

### **Inverting diagonal matrices**

**Theorem** A diagonal matrix  $D = \operatorname{diag}(d_1, \ldots, d_n)$  is invertible if and only if all diagonal entries are nonzero:  $d_i \neq 0$  for  $1 \leq i \leq n$ .

If D is invertible then  $D^{-1} = \operatorname{diag}(d_1^{-1}, \dots, d_n^{-1})$ .

$$egin{pmatrix} d_1 & 0 & \dots & 0 \ 0 & d_2 & \dots & 0 \ dots & dots & \ddots & dots \ 0 & 0 & \dots & d_n \end{pmatrix}^{-1} = egin{pmatrix} d_1^{-1} & 0 & \dots & 0 \ 0 & d_2^{-1} & \dots & 0 \ dots & dots & \ddots & dots \ 0 & 0 & \dots & d_n^{-1} \end{pmatrix}$$

## **Inverting diagonal matrices**

**Theorem** A diagonal matrix  $D = \operatorname{diag}(d_1, \ldots, d_n)$  is invertible if and only if all diagonal entries are nonzero:  $d_i \neq 0$  for  $1 \leq i \leq n$ .

If D is invertible then  $D^{-1} = \operatorname{diag}(d_1^{-1}, \dots, d_n^{-1})$ .

*Proof:* If all  $d_i \neq 0$  then, clearly,  $\operatorname{diag}(d_1, \ldots, d_n) \operatorname{diag}(d_1^{-1}, \ldots, d_n^{-1}) = \operatorname{diag}(1, \ldots, 1) = I$ ,  $\operatorname{diag}(d_1^{-1}, \ldots, d_n^{-1}) \operatorname{diag}(d_1, \ldots, d_n) = \operatorname{diag}(1, \ldots, 1) = I$ .

Now suppose that  $d_i = 0$  for some i. Then for any  $n \times n$  matrix B the ith row of the matrix DB is a zero row. Hence  $DB \neq I$ .

# Inverting 2×2 matrices

*Definition.* The **determinant** of a  $2\times 2$  matrix  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  is  $\det A = ad - bc$ .

**Theorem** A matrix  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  is invertible if and only if det  $A \neq 0$ .

If  $\det A \neq 0$  then

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}.$$

**Theorem** A matrix  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  is invertible if

and only if 
$$\det A \neq 0$$
. If  $\det A \neq 0$  then
$$\begin{pmatrix} a & b \\ C & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -C & a \end{pmatrix}.$$

Proof: Let 
$$B=\begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$
. Then 
$$AB=BA=\begin{pmatrix} ad-bc & 0 \\ 0 & ad-bc \end{pmatrix}=(ad-bc)l_2.$$

In the case  $\det A \neq 0$ , we have  $A^{-1} = (\det A)^{-1}B$ . In the case  $\det A = 0$ , the matrix A is not invertible as otherwise  $AB = O \implies A^{-1}(AB) = A^{-1}O = O$   $\implies (A^{-1}A)B = O \implies I_2B = O \implies B = O$   $\implies A = O$ , but the zero matrix is singular.