MATH 311 Topics in Applied Mathematics I Lecture 6: Diagonal matrices. Inverse matrix.

Diagonal matrices

If $A = (a_{ij})$ is a square matrix, then the entries a_{ii} are called **diagonal entries**. A square matrix is called **diagonal** if all non-diagonal entries are zeros.

Example.
$$\begin{pmatrix} 7 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$
, denoted diag $(7, 1, 2)$.

Let
$$A = \text{diag}(s_1, s_2, ..., s_n)$$
, $B = \text{diag}(t_1, t_2, ..., t_n)$.
Then $A + B = \text{diag}(s_1 + t_1, s_2 + t_2, ..., s_n + t_n)$,
 $rA = \text{diag}(rs_1, rs_2, ..., rs_n)$.

Example.

$$\begin{pmatrix} 7 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 3 \end{pmatrix} = \begin{pmatrix} -7 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 6 \end{pmatrix}$$

Theorem Let $A = \operatorname{diag}(s_1, s_2, \ldots, s_n)$, $B = \operatorname{diag}(t_1, t_2, \ldots, t_n)$.

Then
$$A + B = \text{diag}(s_1 + t_1, s_2 + t_2, \dots, s_n + t_n),$$

 $rA = \text{diag}(rs_1, rs_2, \dots, rs_n).$
 $AB = \text{diag}(s_1t_1, s_2t_2, \dots, s_nt_n).$

In particular, diagonal matrices always commute (i.e., AB = BA).

Example.

$$\begin{pmatrix} 7 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} = \begin{pmatrix} 7a_{11} & 7a_{12} & 7a_{13} \\ a_{21} & a_{22} & a_{23} \\ 2a_{31} & 2a_{32} & 2a_{33} \end{pmatrix}$$

Theorem Let $D = \text{diag}(d_1, d_2, \ldots, d_m)$ and A be an $m \times n$ matrix. Then the matrix DA is obtained from A by multiplying the *i*th row by d_i for $i = 1, 2, \ldots, m$:

$$A = \begin{pmatrix} \mathbf{v}_1 \\ \mathbf{v}_2 \\ \vdots \\ \mathbf{v}_m \end{pmatrix} \implies DA = \begin{pmatrix} d_1 \mathbf{v}_1 \\ d_2 \mathbf{v}_2 \\ \vdots \\ d_m \mathbf{v}_m \end{pmatrix}$$

Example.

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \begin{pmatrix} 7 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} = \begin{pmatrix} 7a_{11} & a_{12} & 2a_{13} \\ 7a_{21} & a_{22} & 2a_{23} \\ 7a_{31} & a_{32} & 2a_{33} \end{pmatrix}$$

Theorem Let $D = \text{diag}(d_1, d_2, \ldots, d_n)$ and A be an $m \times n$ matrix. Then the matrix AD is obtained from A by multiplying the *i*th column by d_i for $i = 1, 2, \ldots, n$:

$$A = (\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_n)$$

$$\implies AD = (d_1 \mathbf{w}_1, d_2 \mathbf{w}_2, \dots, d_n \mathbf{w}_n)$$

Identity matrix

Definition. The **identity matrix** (or **unit matrix**) is a diagonal matrix with all diagonal entries equal to 1. The $n \times n$ identity matrix is denoted I_n or simply I.

$$I_1 = (1), \quad I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad I_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

In general, $I = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{pmatrix}.$

Theorem. Let A be an arbitrary $m \times n$ matrix. Then $I_m A = A I_n = A$.

Inverse matrix

Let $\mathcal{M}_n(\mathbb{R})$ denote the set of all $n \times n$ matrices with real entries. We can **add**, **subtract**, and **multiply** elements of $\mathcal{M}_n(\mathbb{R})$. What about **division**?

Definition. Let $A \in \mathcal{M}_n(\mathbb{R})$. Suppose there exists an $n \times n$ matrix B such that

$$AB = BA = I_n.$$

Then the matrix A is called **invertible** and B is called the **inverse** of A (denoted A^{-1}).

A non-invertible square matrix is called **singular**.

$$AA^{-1} = A^{-1}A = I$$

Examples

$$A = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}, \quad C = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}.$$

$$AB = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix},$$

$$BA = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix},$$

$$C^{2} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}.$$
Thus $A^{-1} = B, \quad B^{-1} = A, \text{ and } C^{-1} = C.$

Basic properties of inverse matrices

• If $B = A^{-1}$ then $A = B^{-1}$. In other words, if A is invertible, so is A^{-1} , and $A = (A^{-1})^{-1}$.

• The inverse matrix (if it exists) is unique. Moreover, if AB = CA = I for some $n \times n$ matrices B and C, then $B = C = A^{-1}$.

Indeed, B = IB = (CA)B = C(AB) = CI = C.

• If $n \times n$ matrices A and B are invertible, so is AB, and $(AB)^{-1} = B^{-1}A^{-1}$.

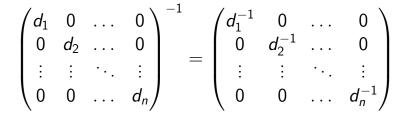
$$(B^{-1}A^{-1})(AB) = B^{-1}(A^{-1}A)B = B^{-1}IB = B^{-1}B = I,$$

 $(AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = AIA^{-1} = AA^{-1} = I.$

• Similarly, $(A_1A_2...A_k)^{-1} = A_k^{-1}...A_2^{-1}A_1^{-1}.$

Inverting diagonal matrices

Theorem A diagonal matrix $D = \text{diag}(d_1, \ldots, d_n)$ is invertible if and only if all diagonal entries are nonzero: $d_i \neq 0$ for $1 \leq i \leq n$. If D is invertible then $D^{-1} = \text{diag}(d_1^{-1}, \ldots, d_n^{-1})$.



Inverting diagonal matrices

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If D is invertible then $D^{-1} = \operatorname{diag}(d_1^{-1}, \ldots, d_n^{-1})$.

Proof: If all $d_i \neq 0$ then, clearly, $\operatorname{diag}(d_1, \ldots, d_n) \operatorname{diag}(d_1^{-1}, \ldots, d_n^{-1}) = \operatorname{diag}(1, \ldots, 1) = I$, $\operatorname{diag}(d_1^{-1}, \ldots, d_n^{-1}) \operatorname{diag}(d_1, \ldots, d_n) = \operatorname{diag}(1, \ldots, 1) = I$. Now suppose that $d_i = 0$ for some *i*. Then for any $n \times n$ matrix *B* the *i*th row of the matrix *DB* is a zero row. Hence $DB \neq I$ as *I* has no zero rows.

Inverting 2×2 matrices

Definition. The **determinant** of a 2×2 matrix $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ is det A = ad - bc.

Theorem A matrix $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ is invertible if and only if det $A \neq 0$.

If det $A \neq 0$ then $\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}.$ **Theorem** A matrix $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ is invertible if and only if det $A \neq 0$. If det $A \neq 0$ then $\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}.$ *Proof:* Let $B = \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$. Then $AB = BA = \begin{pmatrix} ad-bc & 0\\ 0 & ad-bc \end{pmatrix} = (ad-bc)I_2.$

In the case det $A \neq 0$, we have $A^{-1} = (\det A)^{-1}B$. In the case det A = 0, the matrix A is not invertible as otherwise $AB = O \implies A^{-1}(AB) = A^{-1}O = O$ $\implies (A^{-1}A)B = O \implies I_2B = O \implies B = O$ $\implies A = O$, but the zero matrix is singular.