# MATH 311 Topics in Applied Mathematics I

Lecture 5:
Inverse matrix (continued).

Inverse matrix (continued). Transpose of a matrix.

#### **Identity** matrix

Definition. The **identity matrix** (or **unit matrix**) is a diagonal matrix with all diagonal entries equal to 1. The  $n \times n$  identity matrix is denoted  $I_n$  or simply I.

$$I_1=(1), \quad I_2=egin{pmatrix} 1 & 0 \ 0 & 1 \end{pmatrix}, \quad I_3=egin{pmatrix} 1 & 0 & 0 \ 0 & 1 & 0 \ 0 & 0 & 1 \end{pmatrix}.$$

In general, 
$$I = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & & 1 \end{pmatrix}$$
.

**Theorem.** Let A be an arbitrary  $m \times n$  matrix. Then  $I_m A = AI_n = A$ .

#### **Inverse** matrix

Definition. Let A be an  $n \times n$  matrix. The **inverse** of A is an  $n \times n$  matrix, denoted  $A^{-1}$ , such that  $AA^{-1} = A^{-1}A = I.$ 

If  $A^{-1}$  exists then the matrix A is called **invertible**. Otherwise A is called **singular**.

Let A and B be  $n \times n$  matrices. If A is invertible then we can **divide** B by A:

left division:  $A^{-1}B$ , right division:  $BA^{-1}$ .

Remark. There is no notation for the matrix division and the notion is not really used.

## Basic properties of inverse matrices

- If  $B = A^{-1}$  then  $A = B^{-1}$ . In other words, if A is invertible, so is  $A^{-1}$ , and  $A = (A^{-1})^{-1}$ .
- The inverse matrix (if it exists) is unique. Moreover, if AB = CA = I for some  $n \times n$  matrices B and C, then  $B = C = A^{-1}$ .

Indeed, 
$$B = IB = (CA)B = C(AB) = CI = C$$
.

• If  $n \times n$  matrices A and B are invertible, so is AB, and  $(AB)^{-1} = B^{-1}A^{-1}$ .

$$(B^{-1}A^{-1})(AB) = B^{-1}(A^{-1}A)B = B^{-1}IB = B^{-1}B = I,$$
  
 $(AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = AIA^{-1} = AA^{-1} = I.$ 

• Similarly,  $(A_1A_2...A_k)^{-1} = A_k^{-1}...A_2^{-1}A_1^{-1}$ .

### **Inverting diagonal matrices**

**Theorem** A diagonal matrix  $D = \operatorname{diag}(d_1, \ldots, d_n)$  is invertible if and only if all diagonal entries are nonzero:  $d_i \neq 0$  for  $1 \leq i \leq n$ .

If D is invertible then  $D^{-1} = \operatorname{diag}(d_1^{-1}, \dots, d_n^{-1})$ .

$$egin{pmatrix} d_1 & 0 & \dots & 0 \ 0 & d_2 & \dots & 0 \ dots & dots & \ddots & dots \ 0 & 0 & \dots & d_n \end{pmatrix}^{-1} = egin{pmatrix} d_1^{-1} & 0 & \dots & 0 \ 0 & d_2^{-1} & \dots & 0 \ dots & dots & \ddots & dots \ 0 & 0 & \dots & d_n^{-1} \end{pmatrix}$$

## **Inverting diagonal matrices**

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If D is invertible then  $D^{-1} = \operatorname{diag}(d_1^{-1}, \ldots, d_n^{-1})$ .

Proof: If all  $d_i \neq 0$  then, clearly,  $\operatorname{diag}(d_1, \dots, d_n) \operatorname{diag}(d_1^{-1}, \dots, d_n^{-1}) = \operatorname{diag}(1, \dots, 1) = I$ ,  $\operatorname{diag}(d_1^{-1}, \dots, d_n^{-1}) \operatorname{diag}(d_1, \dots, d_n) = \operatorname{diag}(1, \dots, 1) = I$ .

Now suppose that  $d_i = 0$  for some i. Then for any  $n \times n$  matrix B the ith row of the matrix DB is a zero row. Hence  $DB \neq I$  as I has no zero rows.

## Inverting 2×2 matrices

*Definition.* The **determinant** of a  $2\times 2$  matrix  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  is  $\det A = ad - bc$ .

**Theorem** A matrix  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  is invertible if and only if det  $A \neq 0$ .

If  $\det A \neq 0$  then

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}.$$

**Theorem** A matrix  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  is invertible if

and only if 
$$\det A \neq 0$$
. If  $\det A \neq 0$  then

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}.$$

Proof: Let 
$$B = \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$
. Then 
$$AB = BA = \begin{pmatrix} ad-bc & 0 \\ 0 & ad-bc \end{pmatrix} = (ad-bc)I_2.$$

In the case  $\det A \neq 0$ , we have  $A^{-1} = (\det A)^{-1}B$ . In the case  $\det A = 0$ , the matrix A is not invertible as otherwise  $AB = O \implies A^{-1}(AB) = A^{-1}O = O$   $\implies (A^{-1}A)B = O \implies I_2B = O \implies B = O$   $\implies A = O$ , but the zero matrix is singular. **Problem.** Solve a system  $\begin{cases} 4x + 3y = 5, \\ 3x + 2y = -1 \end{cases}$ 

$$\begin{cases} 4x + 3y = 5, \\ 3x + 2y = -1 \end{cases}$$

This system is equivalent to a matrix equation  $A\mathbf{x} = \mathbf{b}$ ,

where 
$$A = \begin{pmatrix} 4 & 3 \\ 3 & 2 \end{pmatrix}$$
,  $\mathbf{x} = \begin{pmatrix} x \\ y \end{pmatrix}$ ,  $\mathbf{b} = \begin{pmatrix} 5 \\ -1 \end{pmatrix}$ .

We have det  $A = -1 \neq 0$ . Hence A is invertible.

$$A\mathbf{x} = \mathbf{b} \implies A^{-1}(A\mathbf{x}) = A^{-1}\mathbf{b} \implies (A^{-1}A)\mathbf{x} = A^{-1}\mathbf{b}$$
  
 $\implies \mathbf{x} = A^{-1}\mathbf{b}$ 

Conversely,  $\mathbf{x} = A^{-1}\mathbf{b} \implies A\mathbf{x} = A(A^{-1}\mathbf{b}) = (AA^{-1})\mathbf{b} = \mathbf{b}$ .

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$$\mathbf{x} = A^{-1}\mathbf{b} \implies A\mathbf{x} = A(A^{-1}\mathbf{b}) = (AA^{-1})\mathbf{b} = \mathbf{b}$$
.

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 4 & 3 \\ 3 & 2 \end{pmatrix}^{-1} \begin{pmatrix} 5 \\ -1 \end{pmatrix} = \frac{1}{-1} \begin{pmatrix} 2 & -3 \\ -3 & 4 \end{pmatrix} \begin{pmatrix} 5 \\ -1 \end{pmatrix} = \begin{pmatrix} -13 \\ 19 \end{pmatrix}$$

System of n linear equations in n variables:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ & \dots \\ a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n \end{cases} \iff A\mathbf{x} = \mathbf{b},$$

where

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix}, \quad \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}.$$

**Theorem** If the matrix A is invertible then the system has a unique solution, which is  $\mathbf{x} = A^{-1}\mathbf{b}$ .

#### General results on inverse matrices

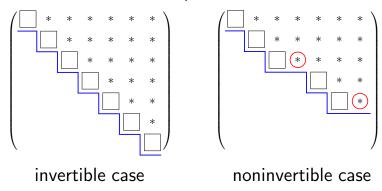
**Theorem 1** Given an  $n \times n$  matrix A, the following conditions are equivalent:

- (i) A is invertible;
- (ii)  $\mathbf{x} = \mathbf{0}$  is the only solution of the matrix equation  $A\mathbf{x} = \mathbf{0}$ ;
- (iii) the matrix equation  $A\mathbf{x} = \mathbf{b}$  has a unique solution for any *n*-dimensional column vector  $\mathbf{b}$ ;
  - (iv) the row echelon form of A has no zero rows;
  - ( $\mathbf{v}$ ) the reduced row echelon form of A is the identity matrix.

**Theorem 2** Suppose that a sequence of elementary row operations converts a matrix A into the identity matrix.

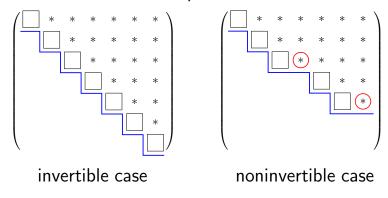
Then the same sequence of operations converts the identity matrix into the inverse matrix  $A^{-1}$ .

#### Row echelon form of a square matrix:



For any matrix in row echelon form, the number of columns with leading entries equals the number of rows with leading entries. For a square matrix, also the number of columns without leading entries (i.e., the number of free variables in a related system of linear equations) equals the number of rows without leading entries (i.e., zero rows).

#### Row echelon form of a square matrix:



Hence the row echelon form of a square matrix A is either strict triangular or else it has a zero row. In the former case, the equation  $A\mathbf{x} = \mathbf{b}$  always has a unique solution. In the latter case,  $A\mathbf{x} = \mathbf{b}$  never has a unique solution. Also, in the former case the reduced row echelon form of A is I.

Example. 
$$A = \begin{pmatrix} 3 & -2 & 0 \\ 1 & 0 & 1 \\ -2 & 3 & 0 \end{pmatrix}$$
.

To check whether A is invertible, we convert it to row echelon form.

Interchange the 1st row with the 2nd row:

$$\begin{pmatrix} 1 & 0 & 1 \\ 3 & -2 & 0 \\ -2 & 3 & 0 \end{pmatrix}$$

Add -3 times the 1st row to the 2nd row:

$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & -2 & -3 \\ -2 & 3 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & -2 & -3 \\ -2 & 3 & 0 \end{pmatrix}$$

Add 2 times the 1st row to the 3rd row:

$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & -2 & -3 \\ 0 & 3 & 2 \end{pmatrix}$$

Multiply the 2nd row by 
$$-0.5$$
:
$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1.5 \\ 0 & 3 & 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1.5 \\ 0 & 3 & 2 \end{pmatrix}$$

Add -3 times the 2nd row to the 3rd row:

$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1.5 \\ 0 & 0 & -2.5 \end{pmatrix}$$

Multiply the 3rd row by 
$$-0.4$$
:

 $\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1.5 \\ 0 & 0 & 1 \end{pmatrix}$ 

We already know that the matrix A is invertible. Let's proceed towards reduced row echelon form.

Add -1.5 times the 3rd row to the 2nd row:

Add 
$$-1.5$$
 times the 3rd row to the 2nd row.

Add 
$$-1$$
 times the 3rd row to the 1st row:

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

To obtain  $A^{-1}$ , we need to apply the following sequence of elementary row operations to the identity matrix:

- interchange the 1st row with the 2nd row,
- add −3 times the 1st row to the 2nd row,
- add 2 times the 1st row to the 3rd row.
- multiply the 2nd row by -0.5,
- add -3 times the 2nd row to the 3rd row,
- multiply the 3rd row by -0.4, • add -1.5 times the 3rd row to the 2nd row,
- add -1 times the 3rd row to the 1st row.

A convenient way to compute the inverse matrix  $A^{-1}$  is to merge the matrices A and I into one  $3\times 6$  matrix  $(A \mid I)$ , and apply elementary row operations to this new matrix.

$$A = \begin{pmatrix} 3 & -2 & 0 \\ 1 & 0 & 1 \\ -2 & 3 & 0 \end{pmatrix}, \qquad I = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$(A \mid I) = \begin{pmatrix} 3 & -2 & 0 \mid 1 & 0 & 0 \\ 1 & 0 & 1 \mid 0 & 1 & 0 \\ -2 & 3 & 0 \mid 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix}
3 & -2 & 0 & 1 & 0 & 0 \\
1 & 0 & 1 & 0 & 1 & 0 \\
-2 & 3 & 0 & 0 & 0 & 1
\end{pmatrix}$$

Interchange the 1st row with the 2nd row:

$$\begin{pmatrix}
1 & 0 & 1 & 0 & 1 & 0 \\
3 & -2 & 0 & 1 & 0 & 0 \\
-2 & 3 & 0 & 0 & 0 & 1
\end{pmatrix}$$

Add -3 times the 1st row to the 2nd row:

$$\begin{pmatrix} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & -2 & -3 & 1 & -3 & 0 \\ -2 & 3 & 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & -2 & -3 & 1 & -3 & 0 \\ -2 & 3 & 0 & 0 & 0 & 1 \end{pmatrix}$$
Add 2 times the 1st row to the 3rd row:

 $\begin{pmatrix} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & -2 & -3 & 1 & -3 & 0 \\ 0 & 3 & 2 & 0 & 2 & 1 \end{pmatrix}$ 

Multiply the 2nd row by 
$$-0.5$$
:
$$\begin{pmatrix}
1 & 0 & 1 & 0 & 1 & 0 \\
0 & 1 & 1.5 & 0 & 0 & 2 & 1
\end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1.5 & -0.5 & 1.5 & 0 \\ 0 & 3 & 2 & 0 & 2 & 1 \end{pmatrix}$$
Add  $-3$  times the 2nd row to the 3rd row:

$$\begin{pmatrix}
1 & 0 & 1 & 0 & 1 & 0 \\
0 & 1 & 1.5 & -0.5 & 1.5 & 0 \\
0 & 0 & -2.5 & 1.5 & -2.5 & 1
\end{pmatrix}$$

Multiply the 3rd row by -0.4:  $\begin{pmatrix}
1 & 0 & 1 & 0 & 1 & 0 \\
0 & 1 & 1.5 & -0.5 & 1.5 & 0 \\
0 & 0 & 1 & -0.6 & 1 & -0.4
\end{pmatrix}$ 

$$\begin{pmatrix}
1 & 0 & 1 \\
0 & 1 & 1.5 \\
0 & 0 & 1
\end{pmatrix}
-0.5 & 1.5 & 0 \\
-0.6 & 1 & -0.4$$

Add -1.5 times the 3rd row to the 2nd row:  $\begin{pmatrix} 1 & 0 & 1 & 0 & 1 & 0 \end{pmatrix}$ 

$$\begin{pmatrix}
1 & 0 & 1 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{pmatrix}
\begin{vmatrix}
0 & 1 & 0 \\
0.4 & 0 & 0.6 \\
-0.6 & 1 & -0.4
\end{pmatrix}$$

Add -1 times the 3rd row to the 1st row:

$$\begin{pmatrix} 1 & 0 & 0 & 0.6 & 0 & 0.4 \\ 0 & 1 & 0 & 0.4 & 0 & 0.6 \\ 0 & 0 & 1 & -0.6 & 1 & -0.4 \end{pmatrix} = (I \mid A^{-1})$$

Thus 
$$\begin{pmatrix} 3 & -2 & 0 \\ 1 & 0 & 1 \\ -2 & 3 & 0 \end{pmatrix}^{-1} = \begin{pmatrix} \frac{3}{5} & 0 & \frac{2}{5} \\ \frac{2}{5} & 0 & \frac{3}{5} \\ -\frac{3}{5} & 1 & -\frac{2}{5} \end{pmatrix}.$$
That is,
$$\begin{pmatrix} 3 & -2 & 0 \\ 1 & 0 & 1 \\ -2 & 3 & 0 \end{pmatrix} \begin{pmatrix} \frac{3}{5} & 0 & \frac{2}{5} \\ \frac{2}{5} & 0 & \frac{3}{5} \\ -\frac{3}{5} & 1 & -\frac{2}{5} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix},$$

$$\begin{pmatrix} \frac{3}{5} & 0 & \frac{2}{5} \\ \frac{2}{5} & 0 & \frac{3}{5} \\ -\frac{3}{5} & 1 & -\frac{2}{5} \end{pmatrix} \begin{pmatrix} 3 & -2 & 0 \\ 1 & 0 & 1 \\ -2 & 3 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

# Why does it work?

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{pmatrix} = \begin{pmatrix} a_1 & a_2 & a_3 \\ 2b_1 & 2b_2 & 2b_3 \\ c_1 & c_2 & c_3 \end{pmatrix},$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{pmatrix} = \begin{pmatrix} a_1 & a_2 & a_3 \\ b_1 + 3a_1 & b_2 + 3a_2 & b_3 + 3a_3 \\ c_1 & c_2 & c_3 \end{pmatrix},$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{pmatrix} = \begin{pmatrix} a_1 & a_2 & a_3 \\ c_1 & c_2 & c_3 \\ b_1 & b_2 & b_3 \end{pmatrix}.$$

**Proposition** Any elementary row operation can be simulated as left multiplication by a certain matrix.

## **Elementary matrices**

$$E=egin{pmatrix}1&&&&&O\ &\ddots&&&O\ &&1&&&&\ &&r&&&&\ &&&1&&&\ &O&&&\ddots&&\ &&&&1\end{pmatrix}$$
 row  $\#i$ 

To obtain the matrix EA from A, multiply the ith row by r. To obtain the matrix AE from A, multiply the ith column by r.

## **Elementary matrices**

$$E = \begin{pmatrix} 1 & & & & & & \\ \vdots & \ddots & & & & O \\ 0 & \cdots & 1 & & & & \\ \vdots & & \vdots & \ddots & & & \\ 0 & \cdots & r & \cdots & 1 & & \\ \vdots & & \vdots & & \vdots & \ddots & \\ 0 & \cdots & 0 & \cdots & 0 & \cdots & 1 \end{pmatrix} \quad \text{row } \# j$$

To obtain the matrix EA from A, add r times the ith row to the jth row. To obtain the matrix AE from A, add r times the jth column to the ith column.

## **Elementary matrices**

To obtain the matrix EA from A, interchange the ith row with the jth row. To obtain AE from A, interchange the ith column with the jth column.

# Why does it work? (continued)

Assume that a square matrix A can be converted to the identity matrix by a sequence of elementary row operations. Then  $E_k E_{k-1} \dots E_2 E_1 A = I$ , where  $E_1, E_2, \dots, E_k$  are elementary matrices simulating those operations.

Applying the same sequence of operations to the identity matrix, we obtain the matrix

$$B = E_k E_{k-1} \dots E_2 E_1 I = E_k E_{k-1} \dots E_2 E_1.$$

Thus BA = I. Besides, B is invertible since elementary matrices are invertible (why?). It follows that  $A = B^{-1}$ , then  $B = A^{-1}$ .

## Transpose of a matrix

Definition. Given a matrix A, the **transpose** of A, denoted  $A^T$ , is the matrix whose rows are columns of A (and whose columns are rows of A). That is, if  $A = (a_{ij})$  then  $A^T = (b_{ij})$ , where  $b_{ij} = a_{ji}$ .

Examples. 
$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}^T = \begin{pmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{pmatrix}$$
,

$$\begin{pmatrix} 7 \\ 8 \\ 9 \end{pmatrix}^T = (7, 8, 9), \qquad \begin{pmatrix} 4 & 7 \\ 7 & 0 \end{pmatrix}^T = \begin{pmatrix} 4 & 7 \\ 7 & 0 \end{pmatrix}.$$

# **Properties of transposes:**

•  $(A_1 A_2 ... A_k)^T = A_k^T ... A_2^T A_1^T$ 

$$\bullet \ (A^T)^T = A$$

$$\bullet (A \mid B)^T =$$

$$\bullet \ (A+B)^T = A^T + B^T$$

$$\bullet (A+B)' =$$

$$\bullet (rA)^T = rA^T$$

$$(A+D)$$
 –

•  $(AB)^T = B^T A^T$ 

 $\bullet$   $(A^{-1})^T = (A^T)^{-1}$ 

Definition. A square matrix A is said to be **symmetric** if  $A^T = A$ .

For example, any diagonal matrix is symmetric.

**Proposition** For any square matrix A the matrices  $B = AA^T$  and  $C = A + A^T$  are symmetric.

Proof.

$$B^{T} = (AA^{T})^{T} = (A^{T})^{T}A^{T} = AA^{T} = B,$$
 $C^{T} = (A + A^{T})^{T} = A^{T} + (A^{T})^{T} = A^{T} + A = C.$ 

$$C^{T} = (A + A^{T})^{T} = A^{T} + (A^{T})^{T} = A^{T} + A = C.$$